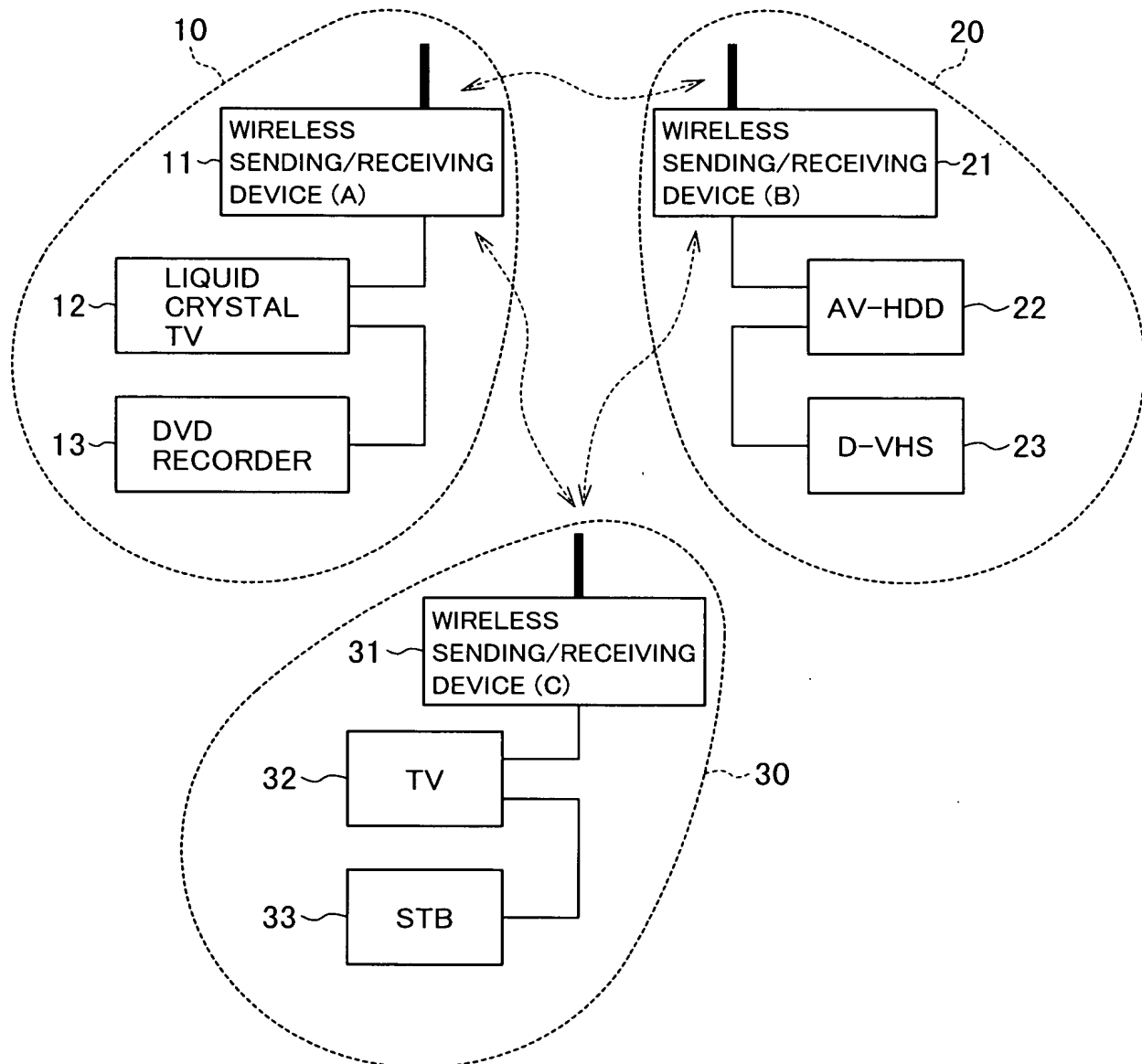


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FIG. 1



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FIG.2

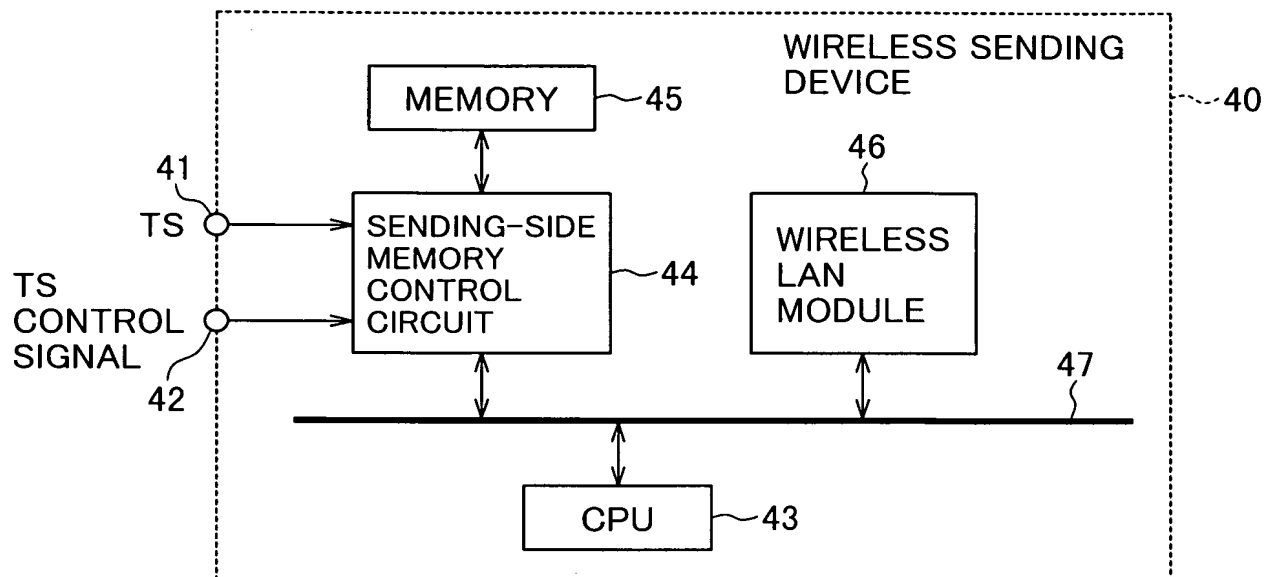
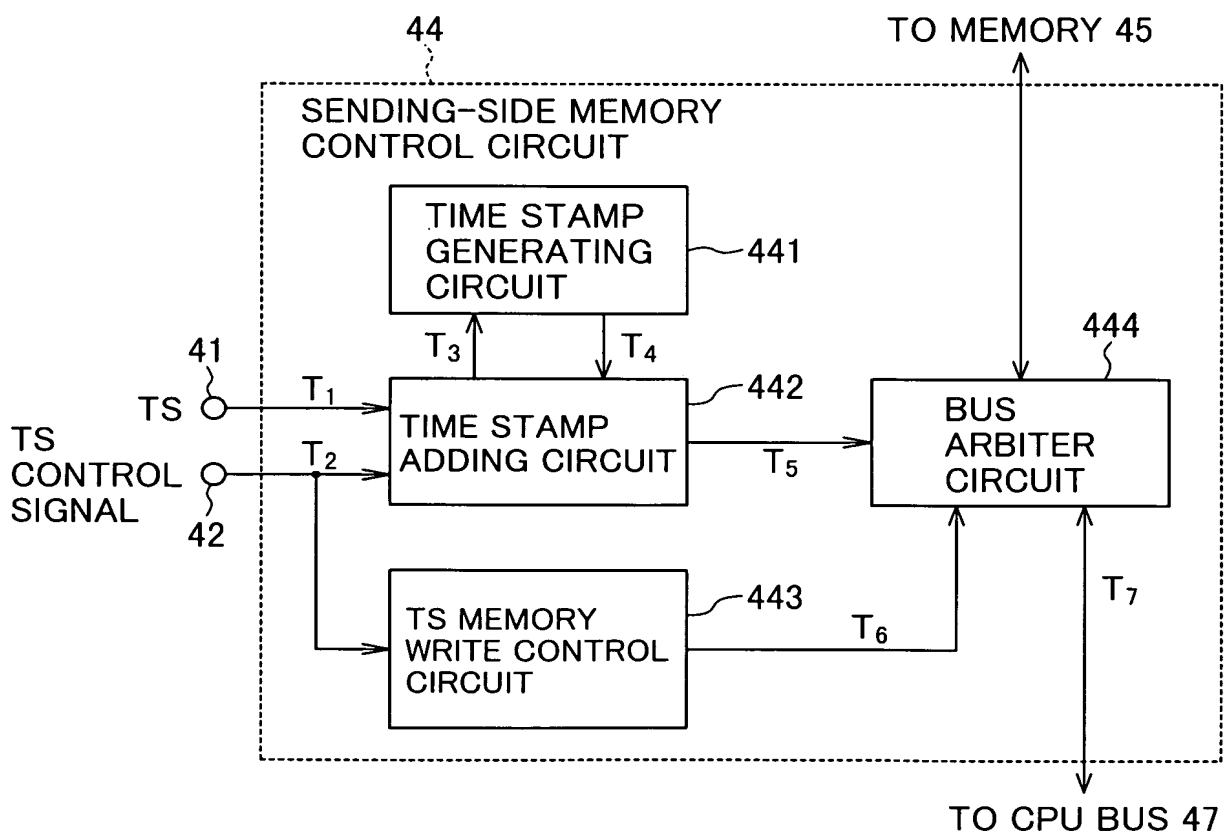


FIG.3



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FIG.4

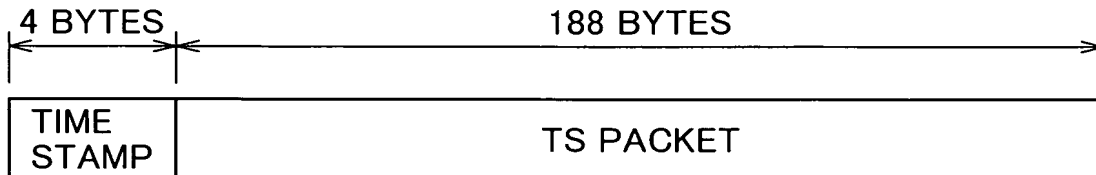
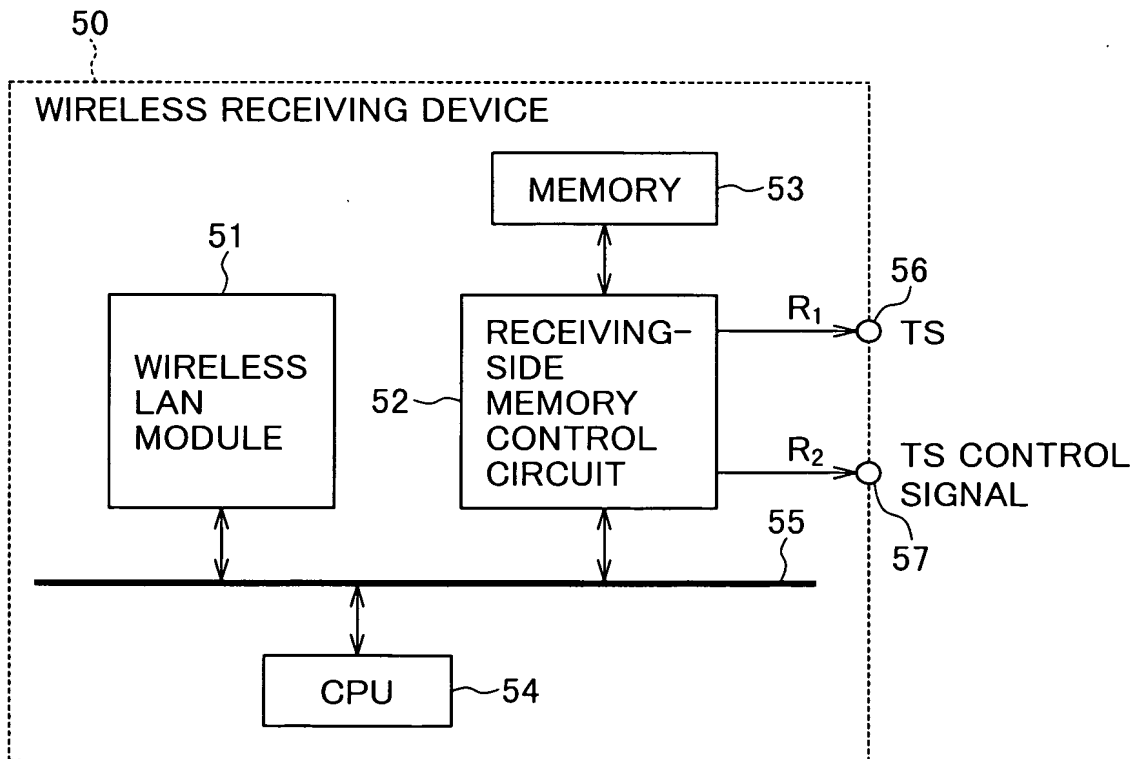


FIG.5



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FIG.6

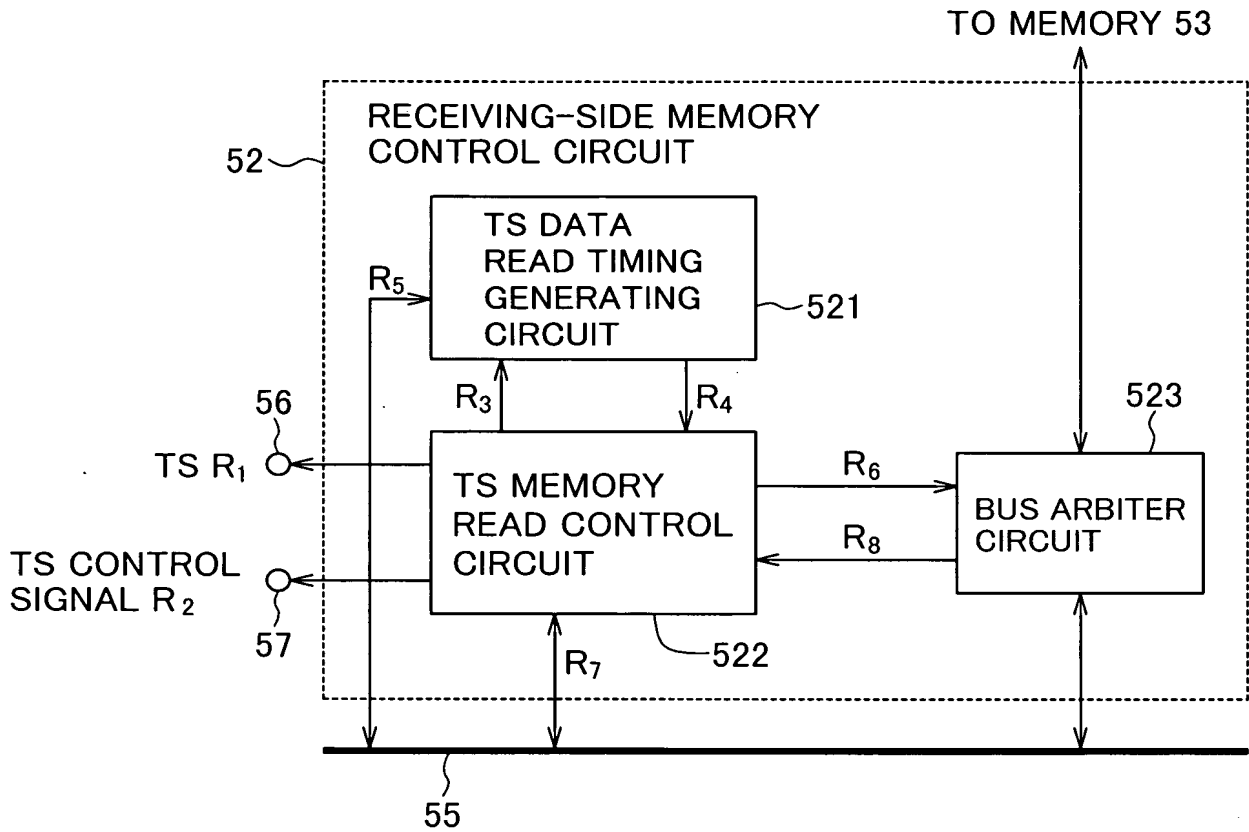


FIG.7

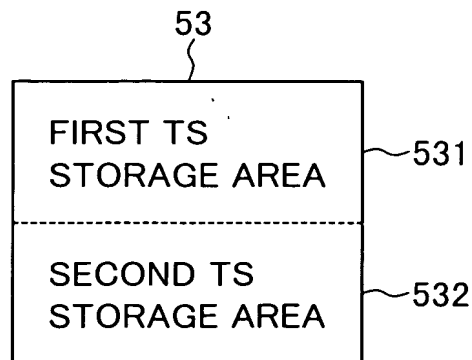
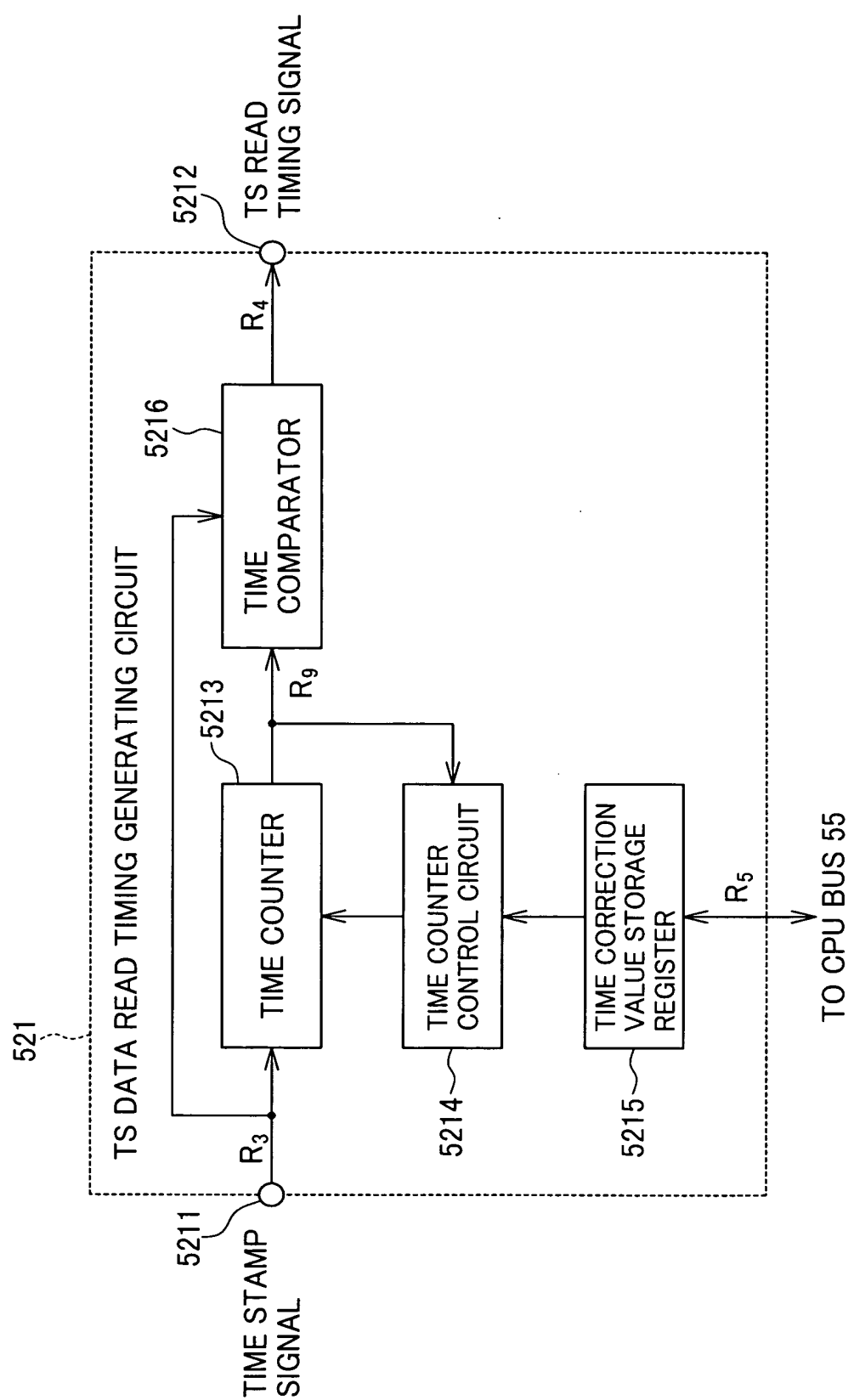


FIG.8



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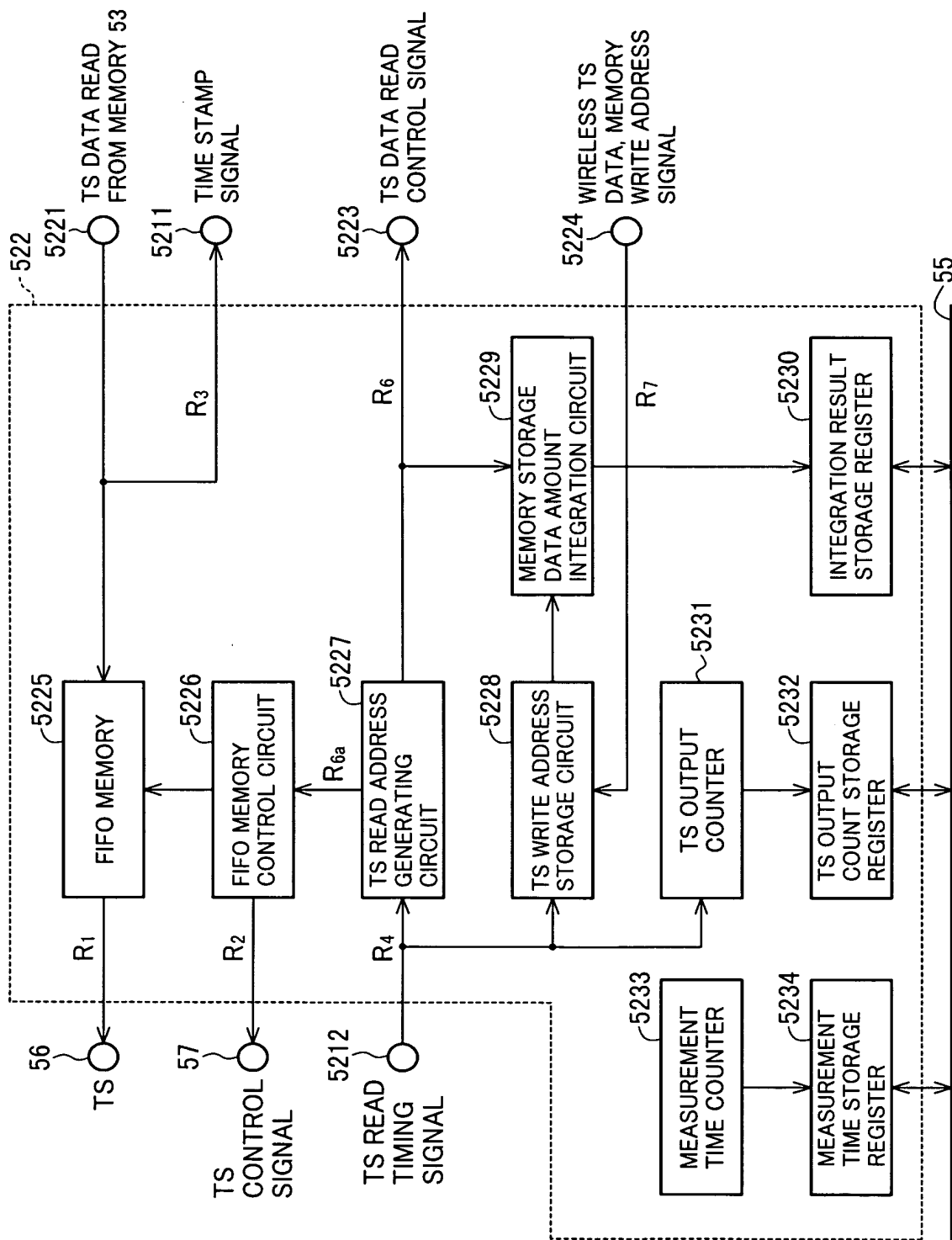
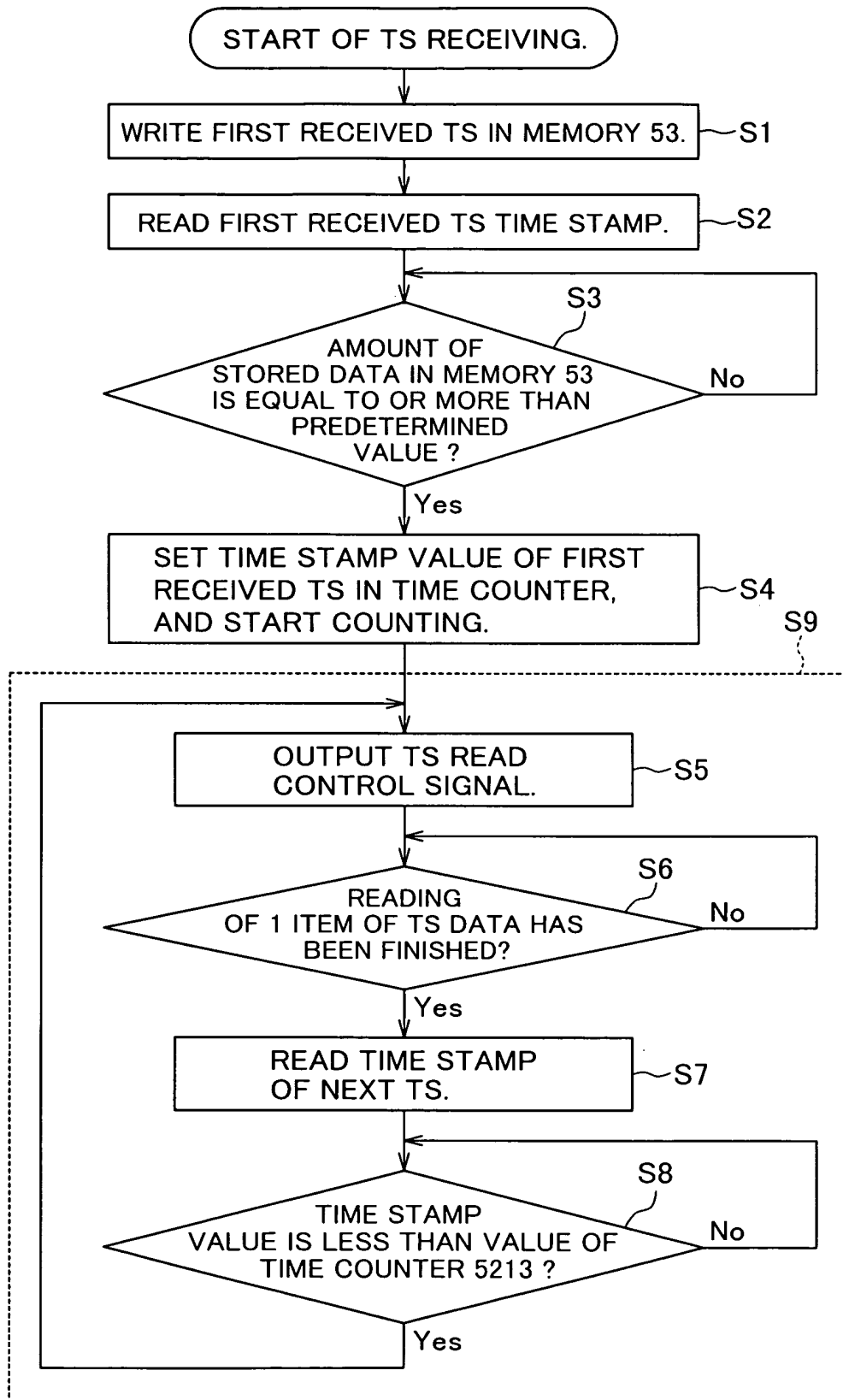


FIG. 9

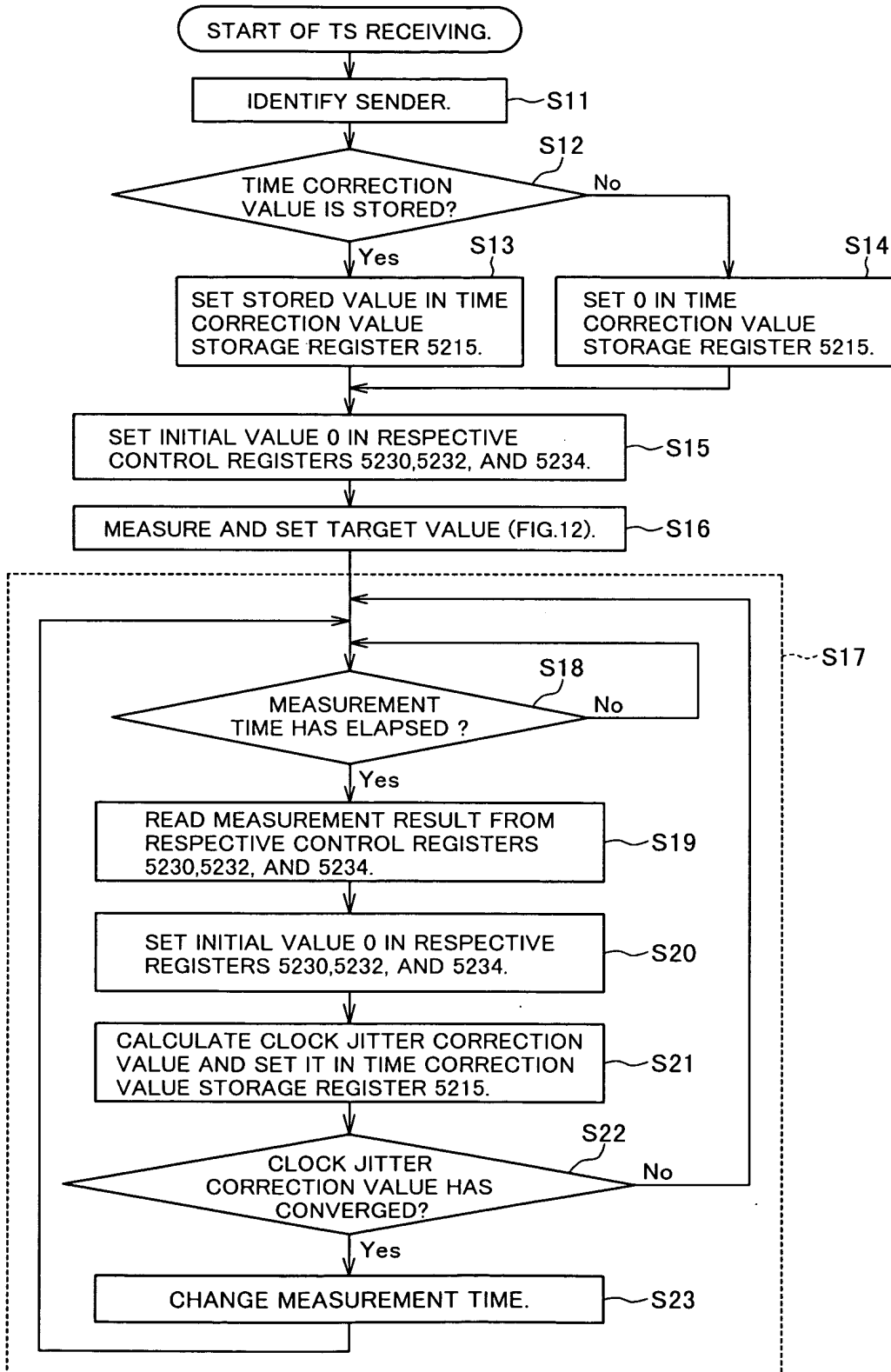
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FIG.10

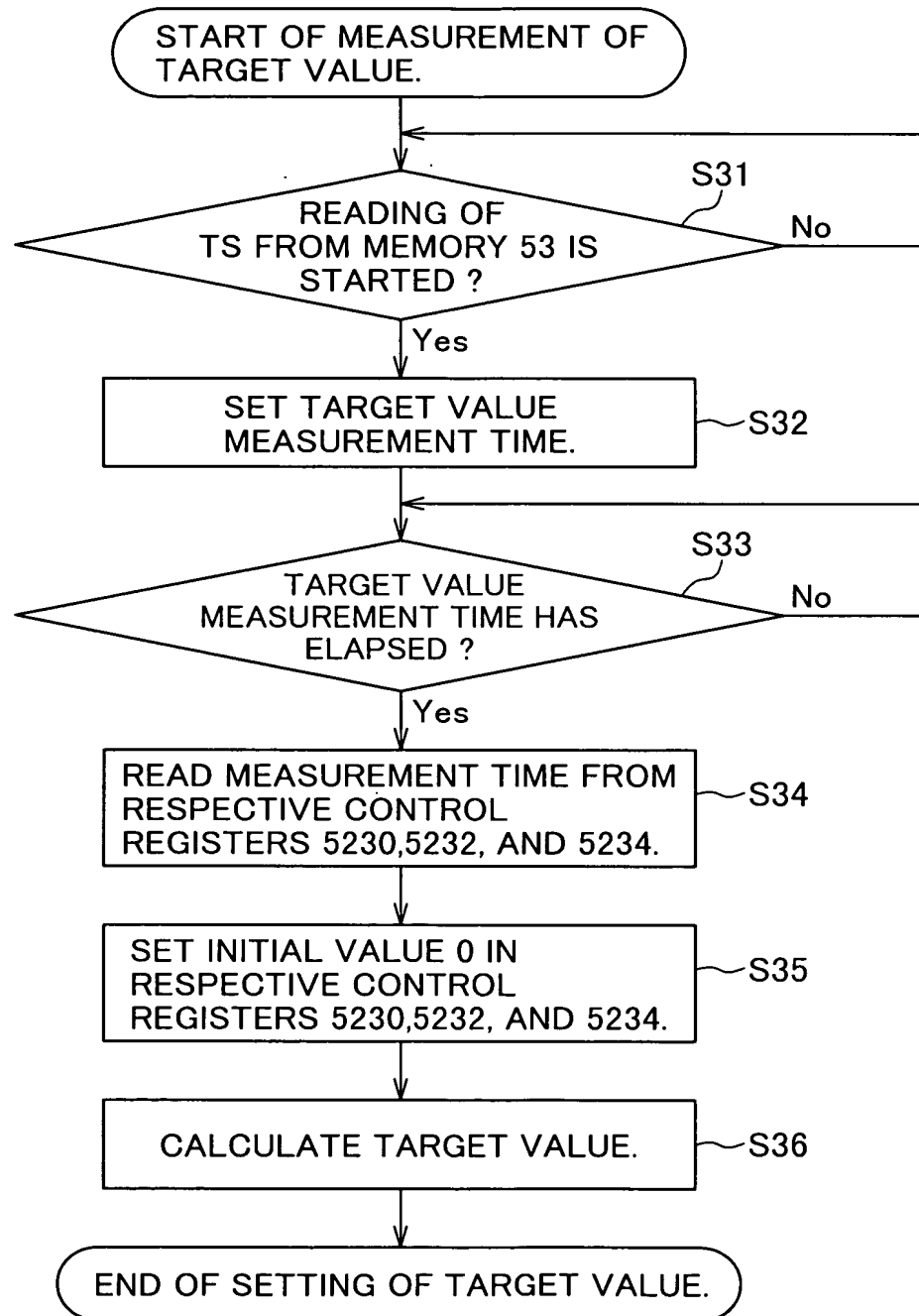


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FIG.11

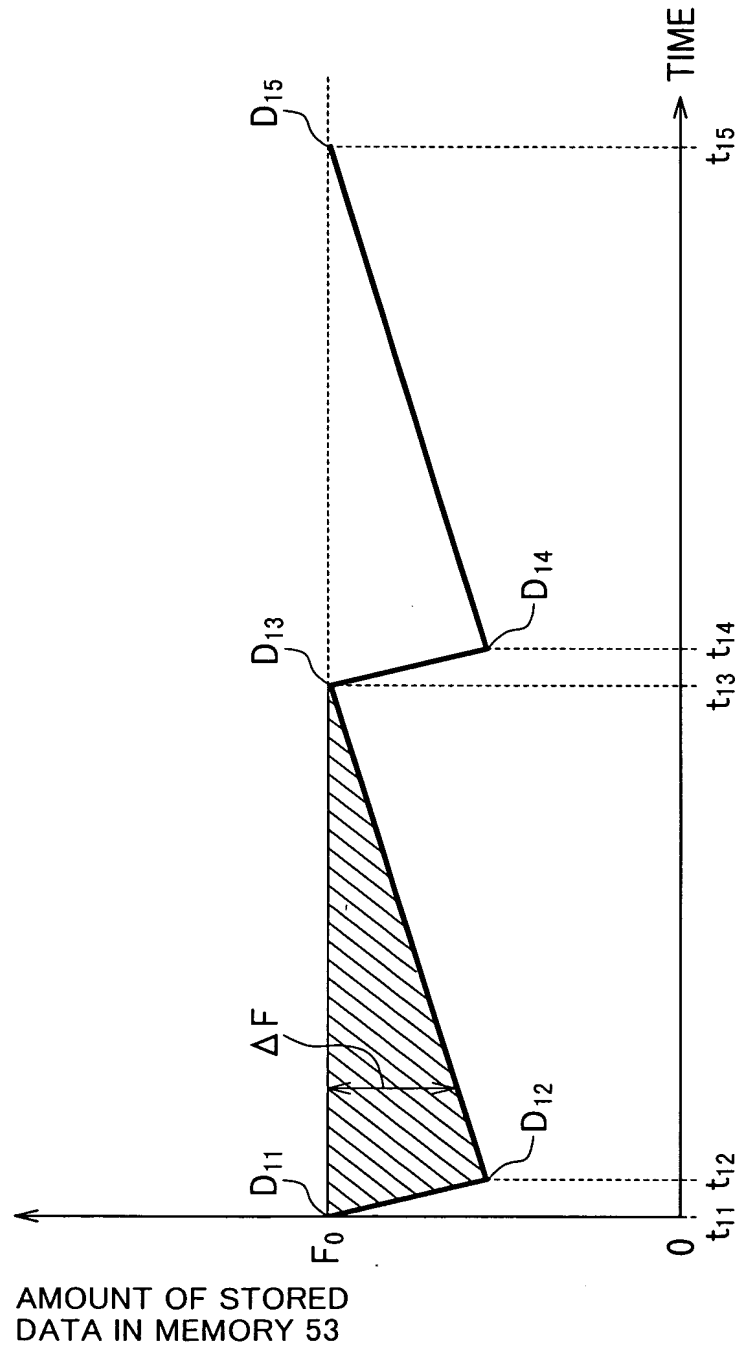


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FIG.12

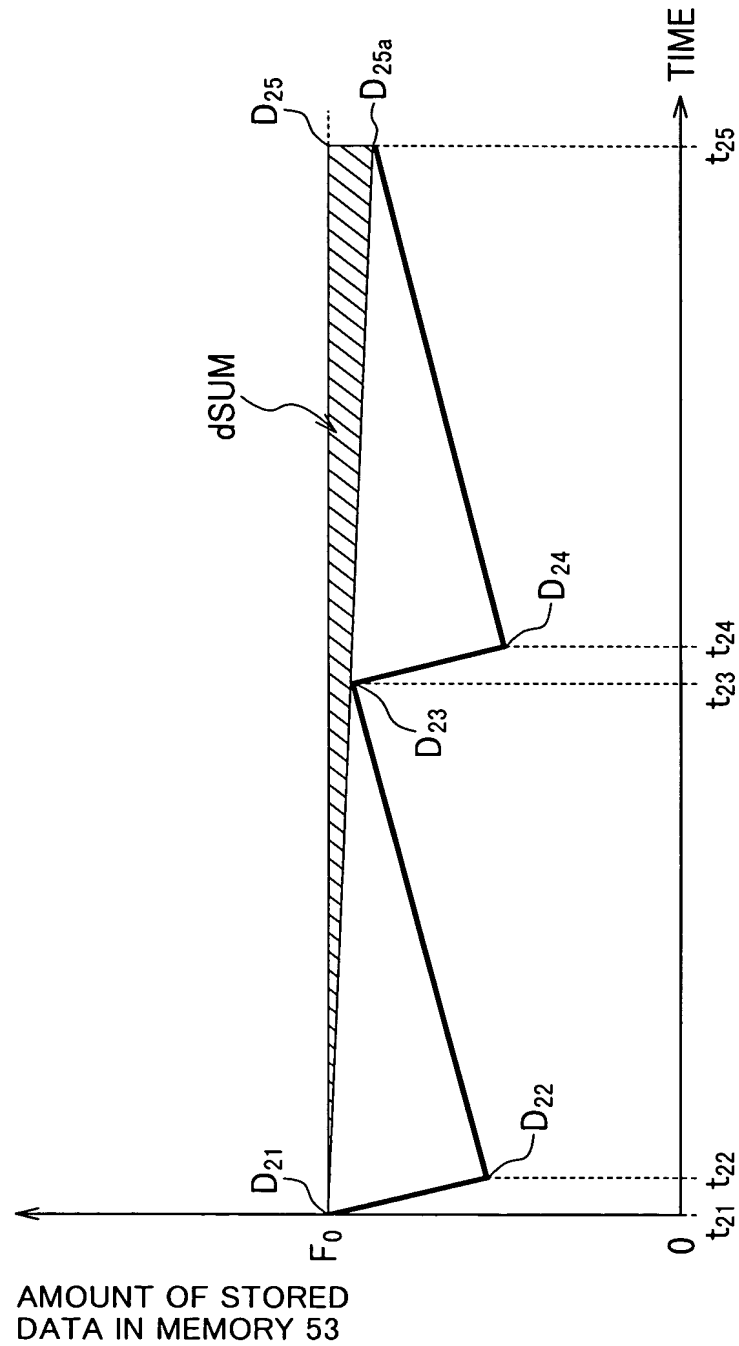
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FIG.13



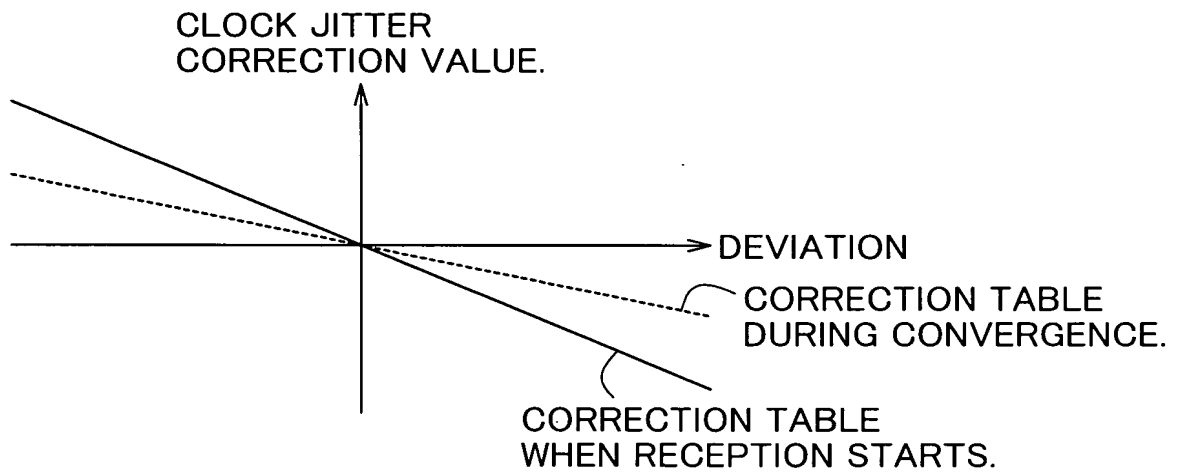
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FIG. 14

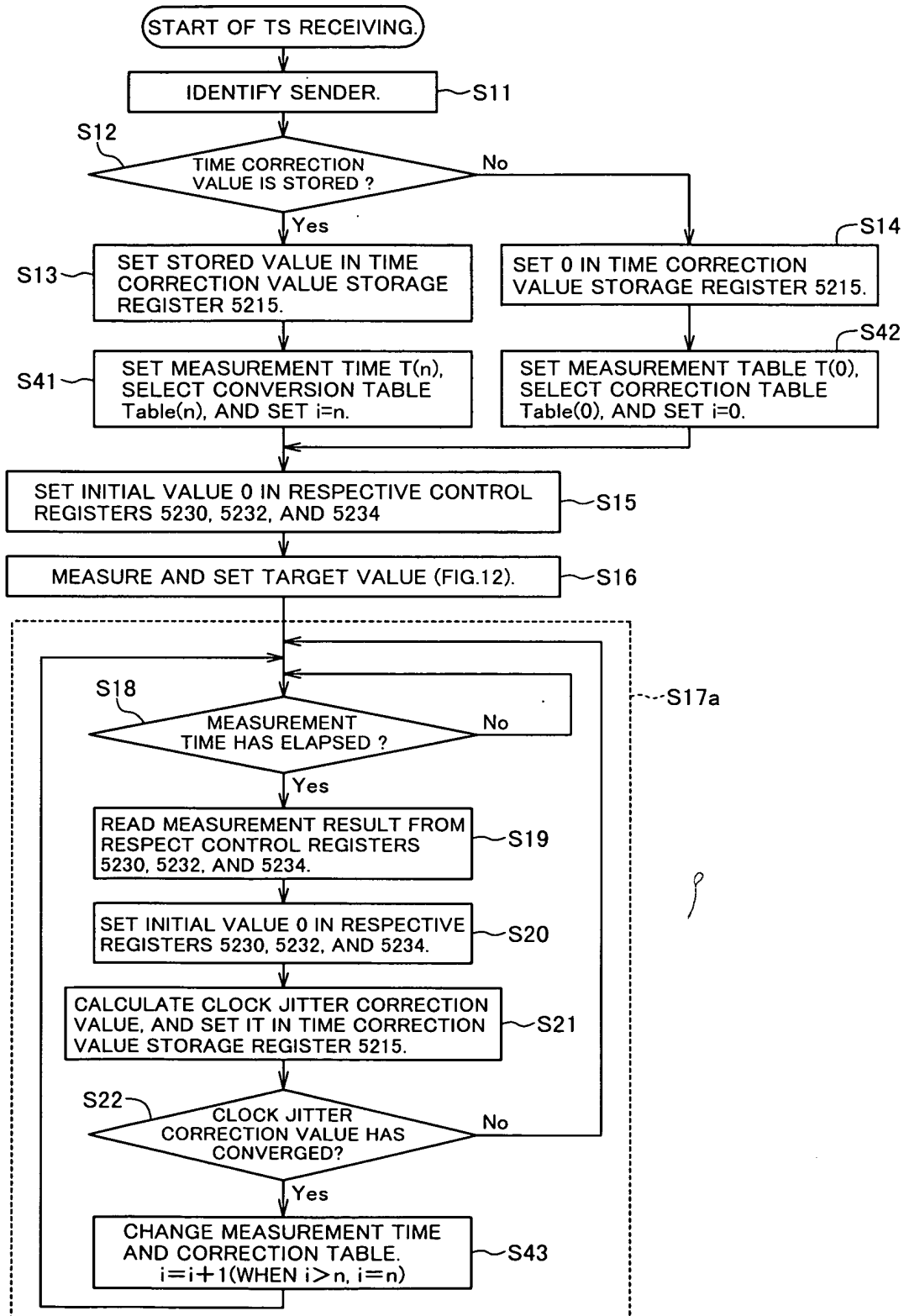


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FIG.15



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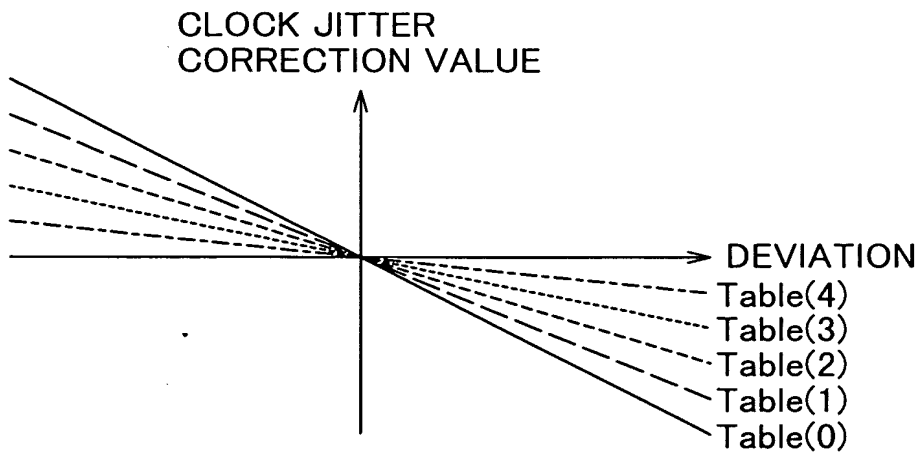
FIG.16

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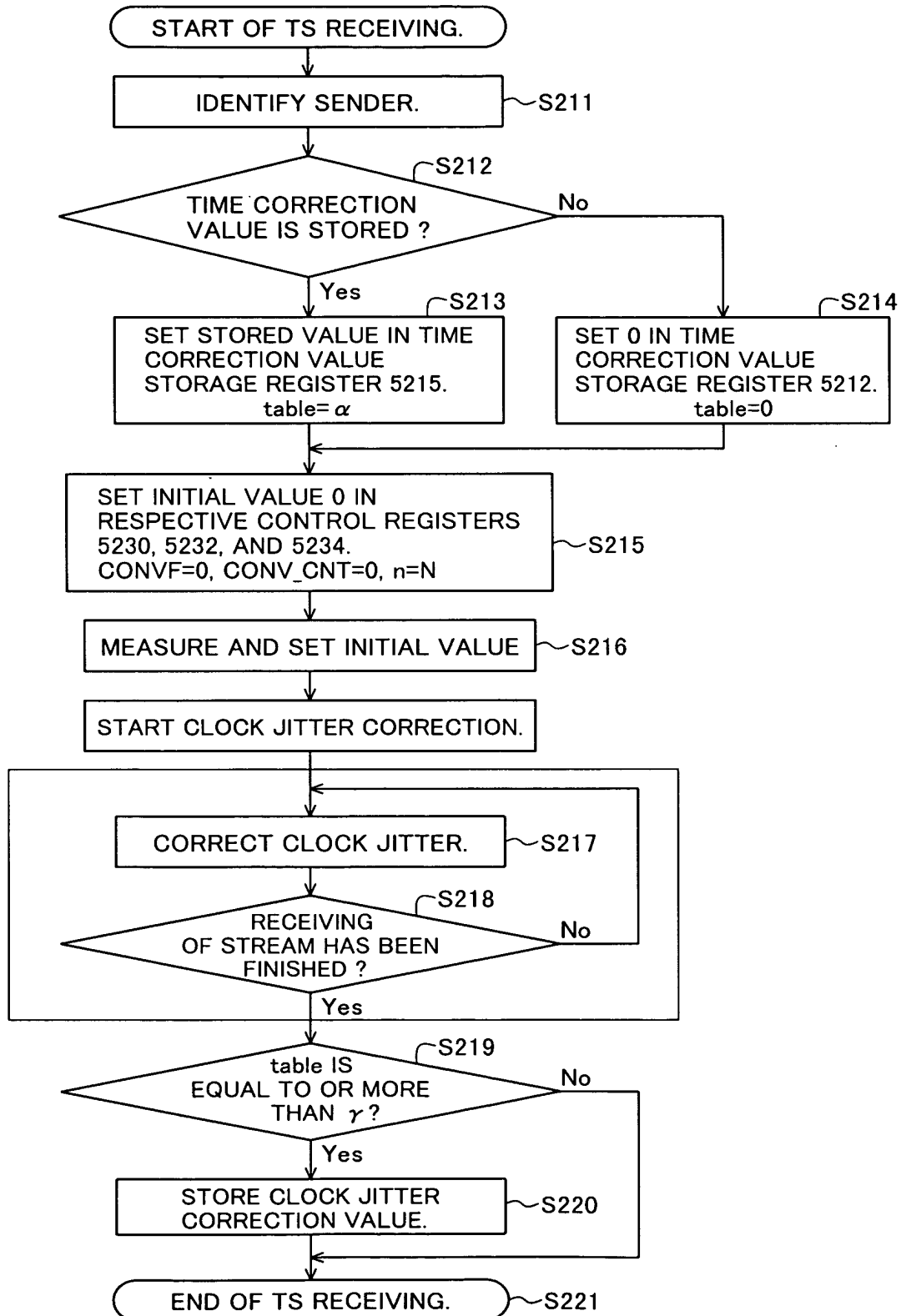
FIG.17

i	MEASUREMENT TIME T(n)	CORRECTION TABLE
0	0.5 SECONDS	Table(0)
1	1.0 SECONDS	Table(1)
2	2.0 SECONDS	Table(2)
3	4.0 SECONDS	Table(3)
4	8.0 SECONDS	Table(4)

FIG.18

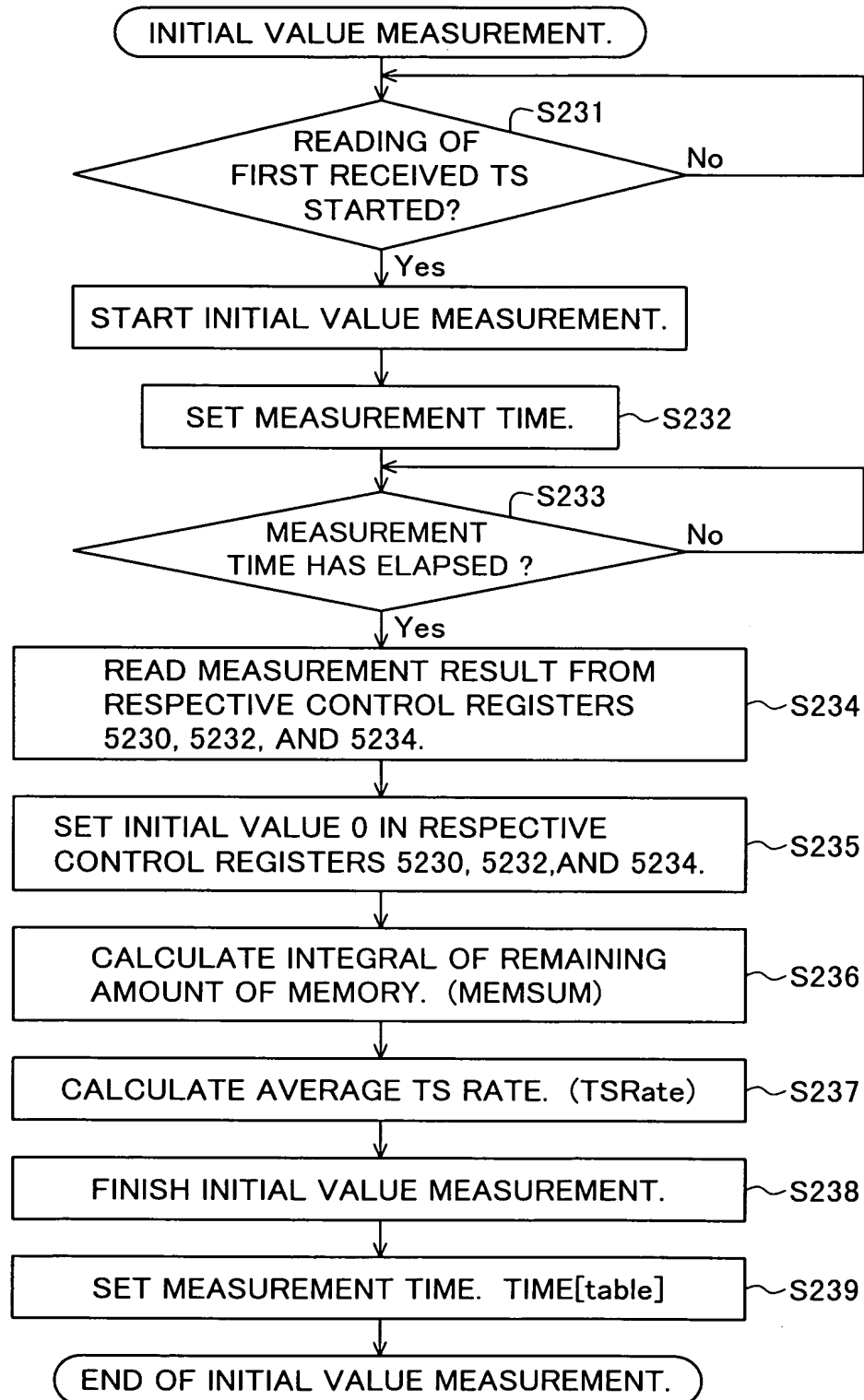


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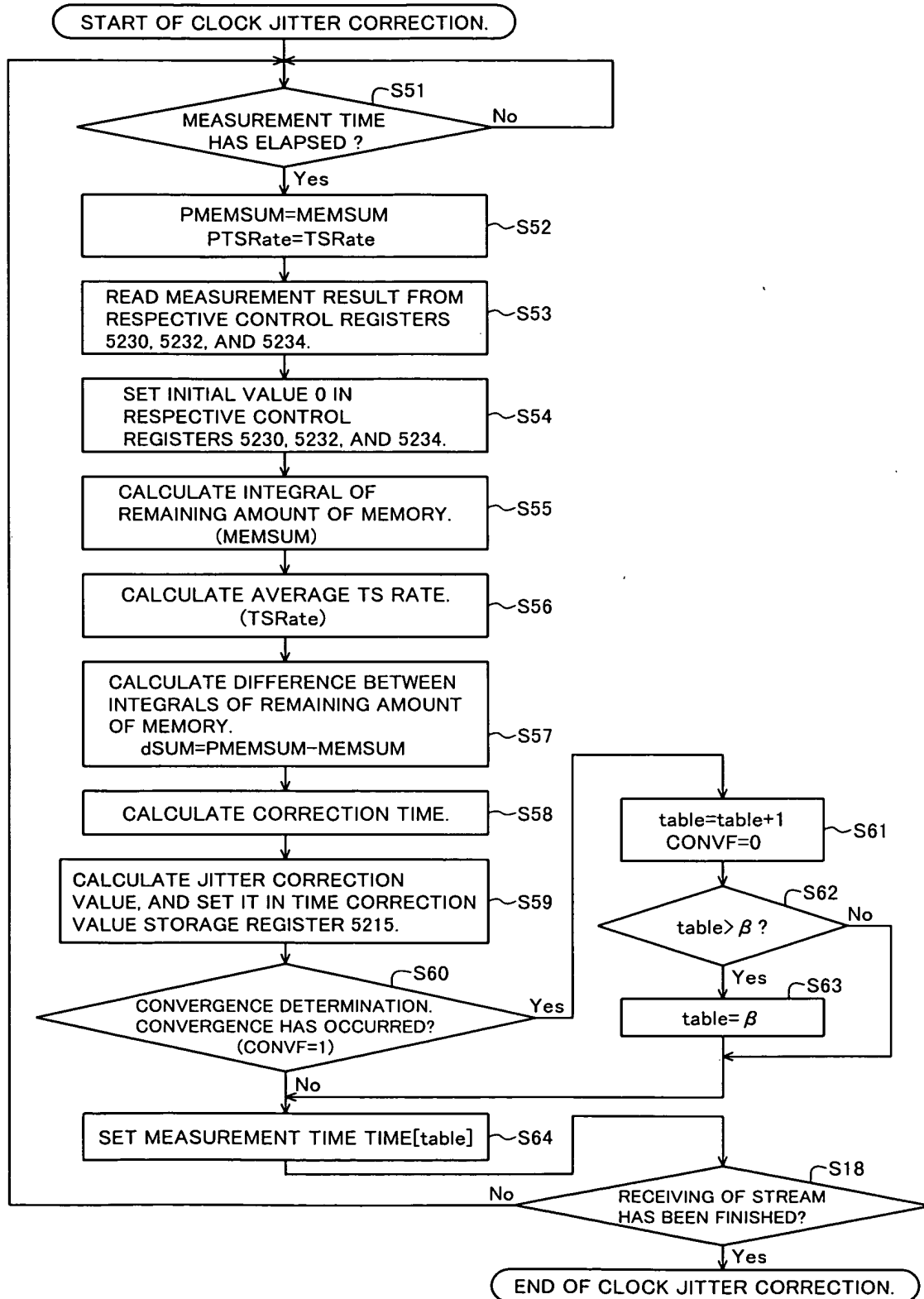
FIG.19

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FIG.20

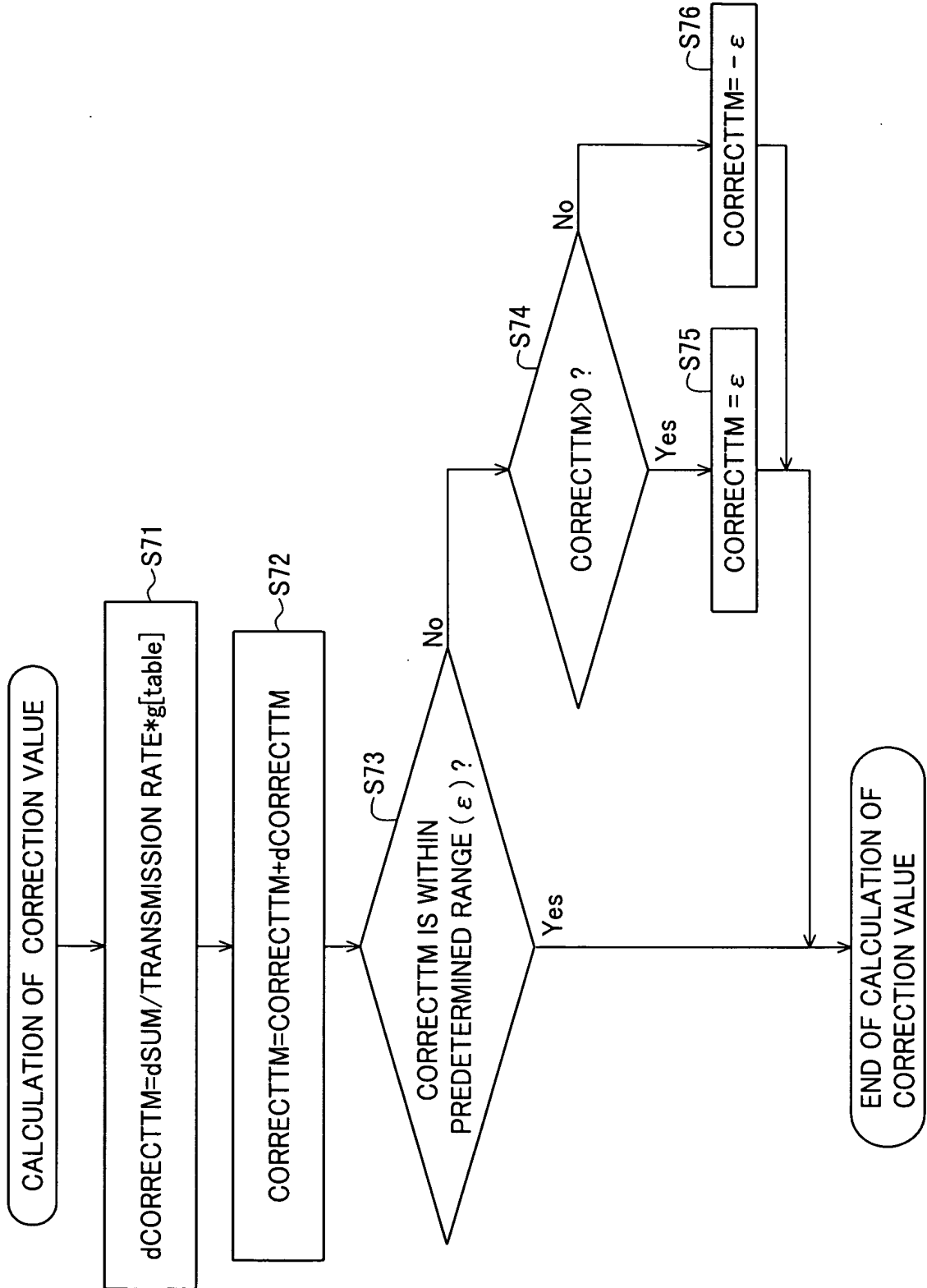


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FIG.21

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FIG.22



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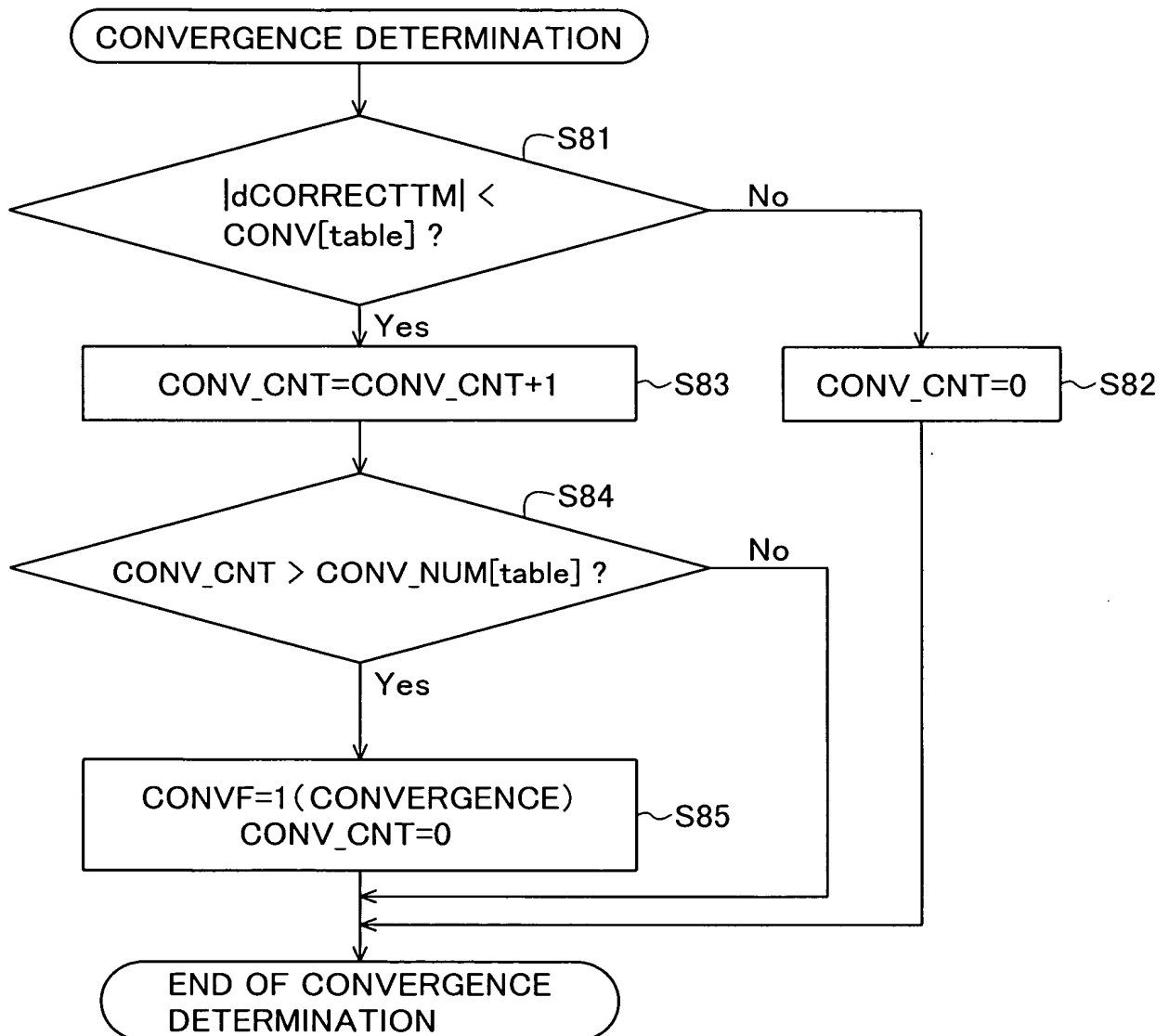
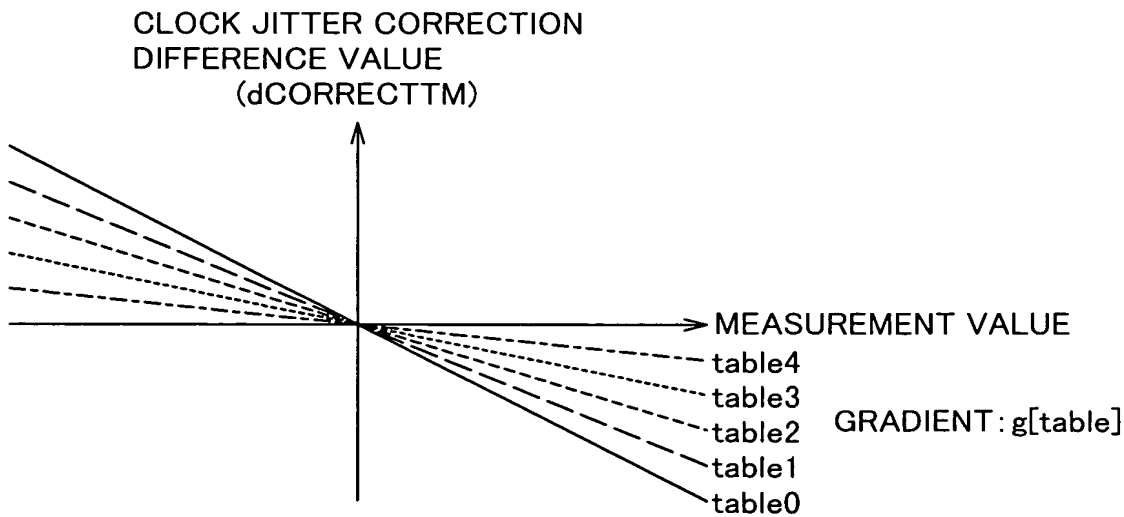
FIG.23

FIG.24

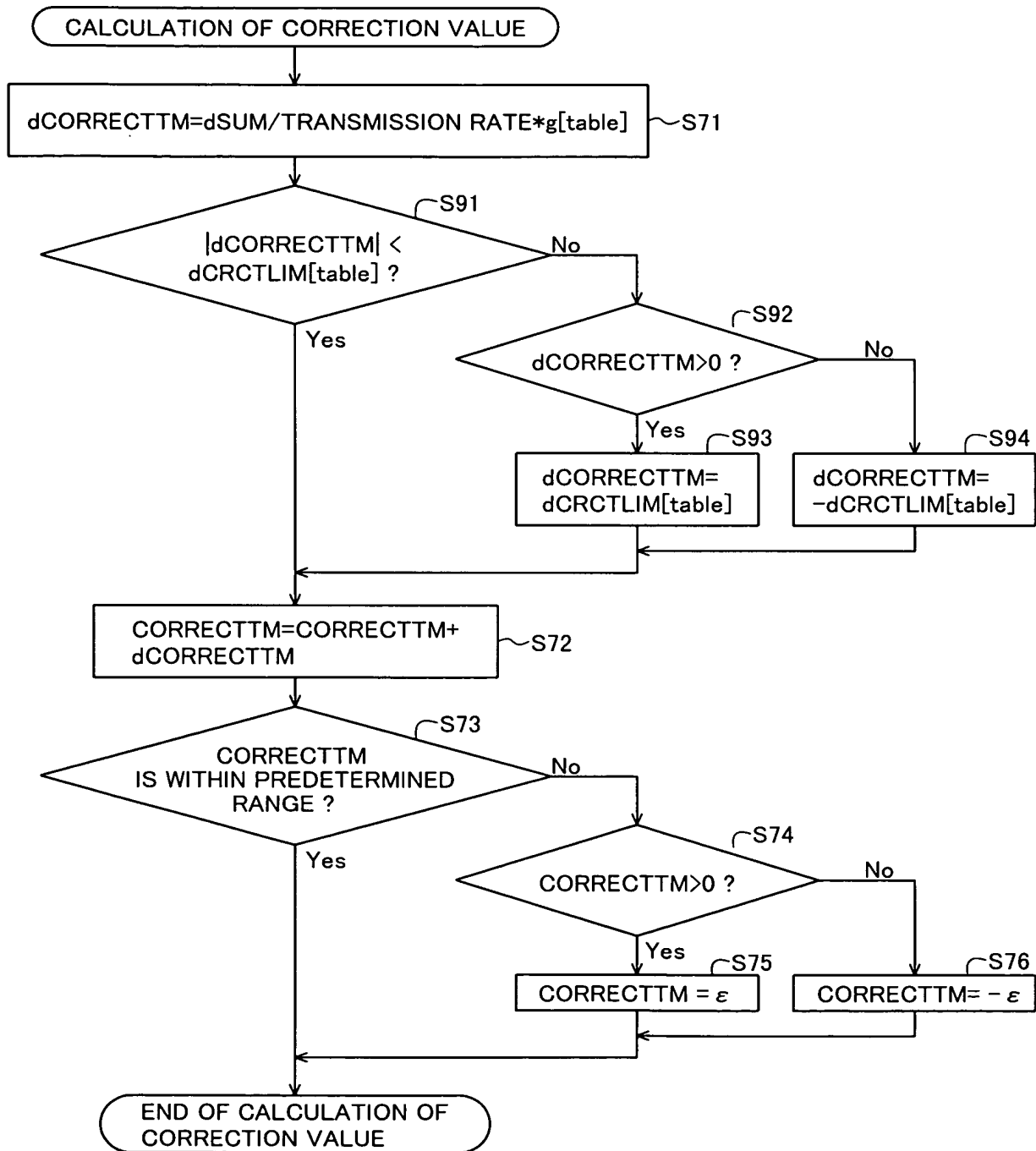
I	MEASUREMENT TIME (TIME)	CONVERGENCE DETERMINATION THRESHOLD (CONV) CRCTML IS PREDETERMINED CONSTANT.	CONVERGENCE DETERMINATION CONDITION (CONV_CNT)	CORRECTION TABLE
0	0.5 SECONDS	CRCTML	10	table0
1	1.0 SECONDS	0.75*CRCTML	15	table1
2	2.0 SECONDS	0.5*CRCTML	20	table2
3	4.0 SECONDS	0.25*CRCTML	25	table3
4	8.0 SECONDS	0.125*CRCTML	30	table4

FIG.25

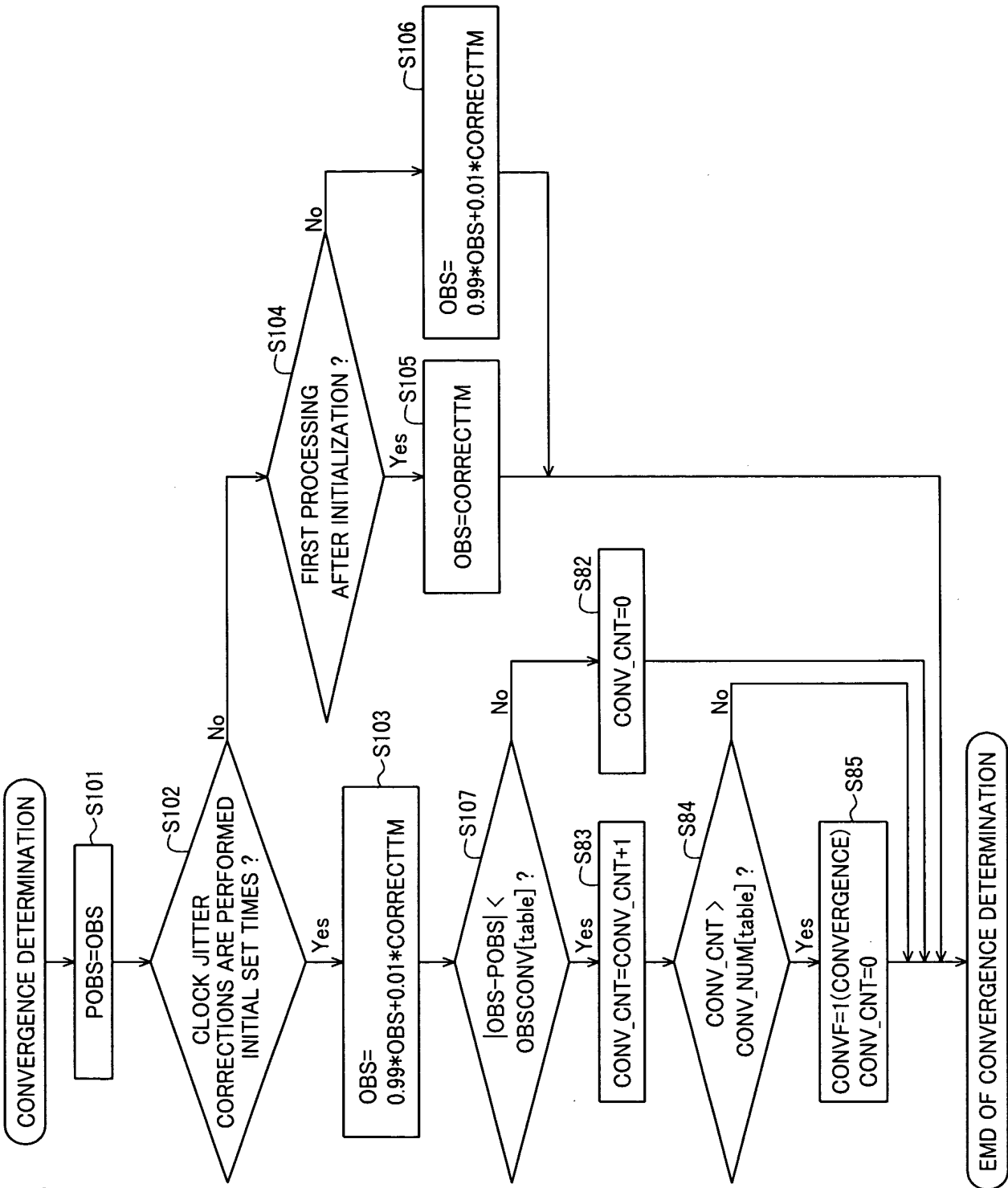


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FIG.26



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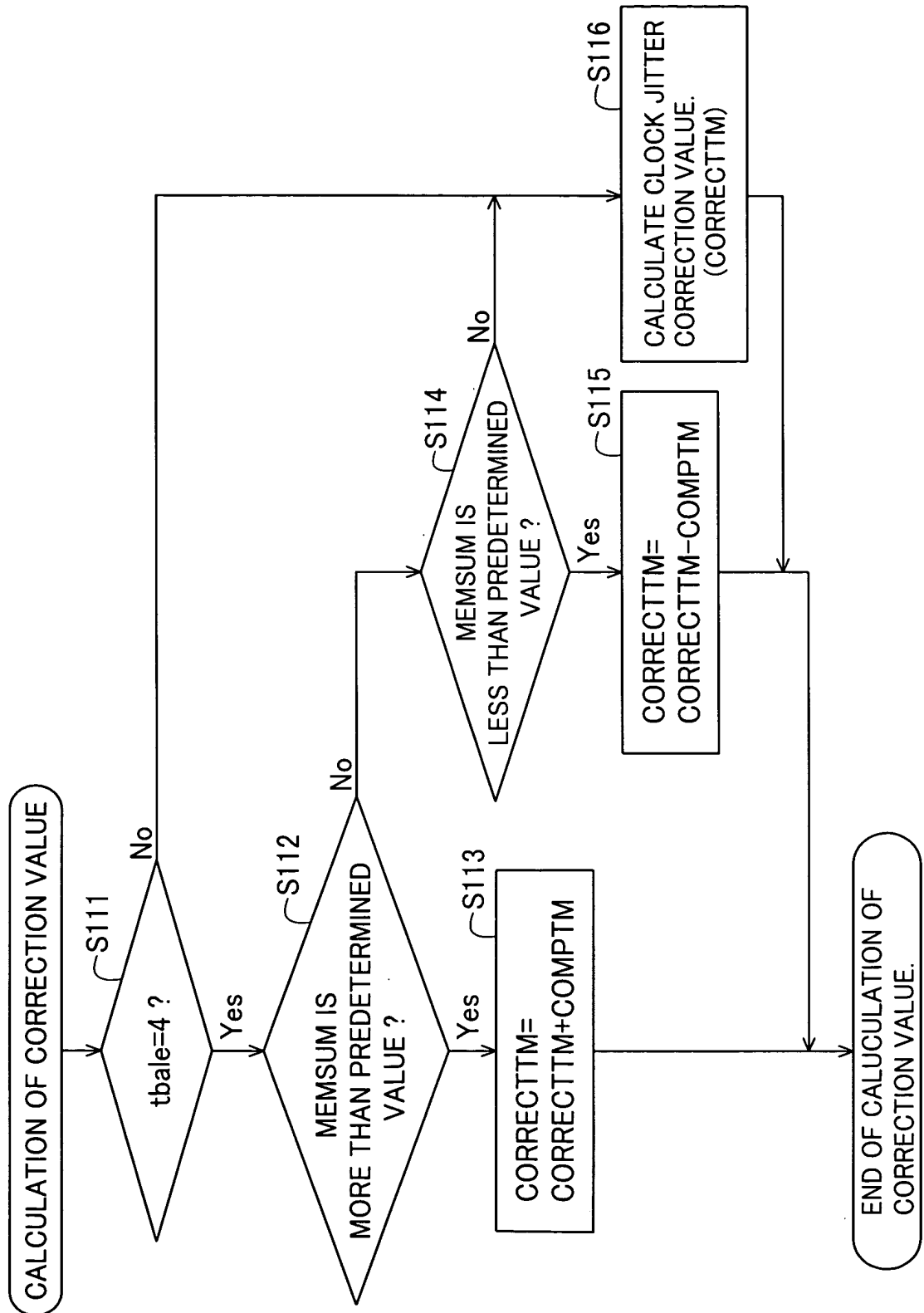
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FIG.28

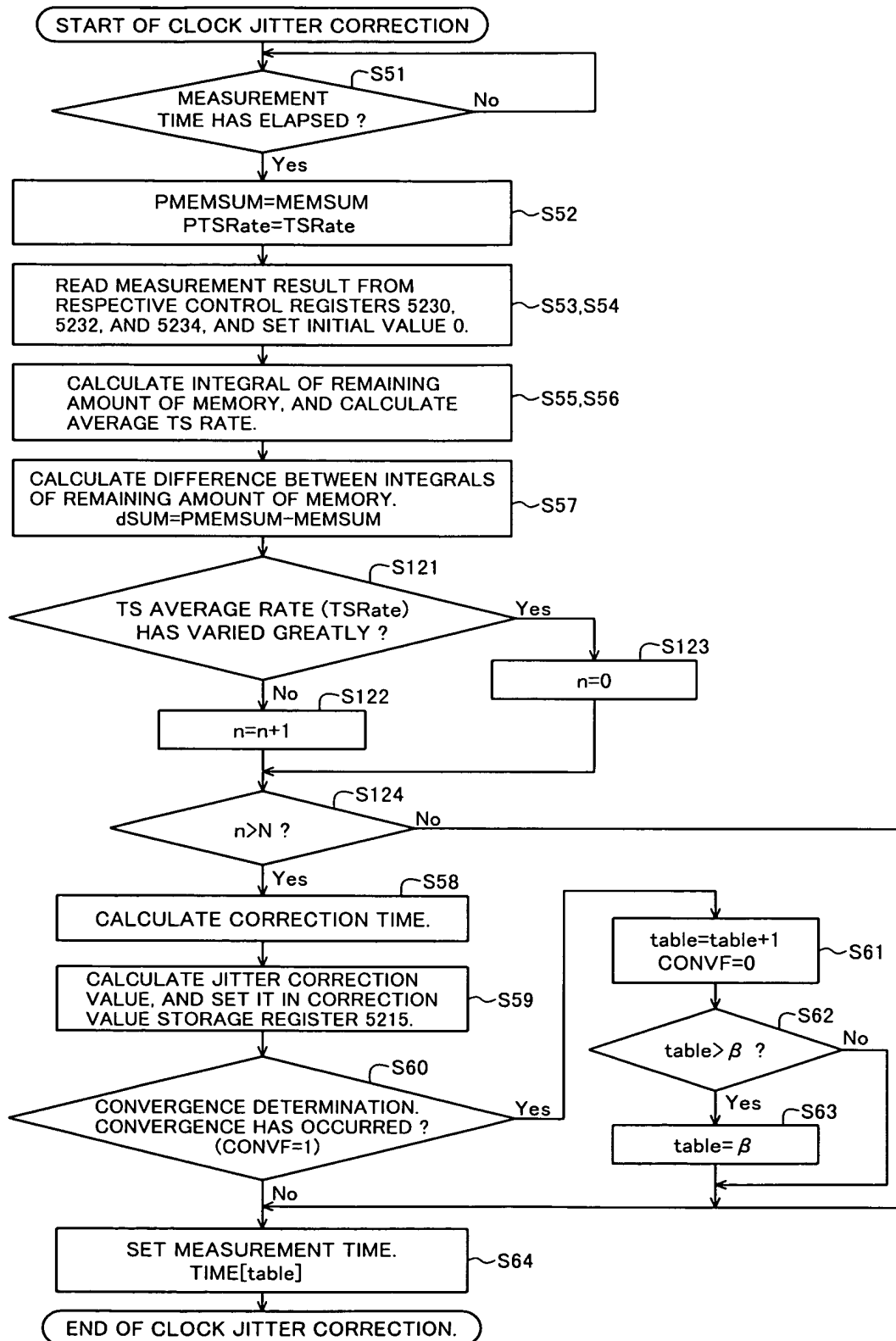
I	MEASUREMENT TIME (TIME)	CONVERGENCE DETERMINATION THRESHOLD (OBSCONV) OBSCRCTML IS PREDETERMINED CONSTANT.	CONVERGENCE DETERMINATION CONDITION (CONV_CNT)	CORRECTION DIFFERENCE RANGE (dCRCTLIM) dCRCTLIM IS PREDETERMINED CONSTANT.	CORRECTION TABLE
0	0.5 SECONDS	OBSCRCTML	10	dCRCTLIM	table0
1	1.0 SECONDS	0.75*OBSCRCTML	15	0.75*dCRCTLIM	table1
2	2.0 SECONDS	0.5*OBSCRCTML	20	0.5*dCRCTLIM	table2
3	4.0 SECONDS	0.25*OBSCRCTML	25	0.25*dCRCTLIM	table3
4	8.0 SECONDS	0.125*OBSCRCTML	30	0.125*dCRCTLIM	table4

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FIG.29

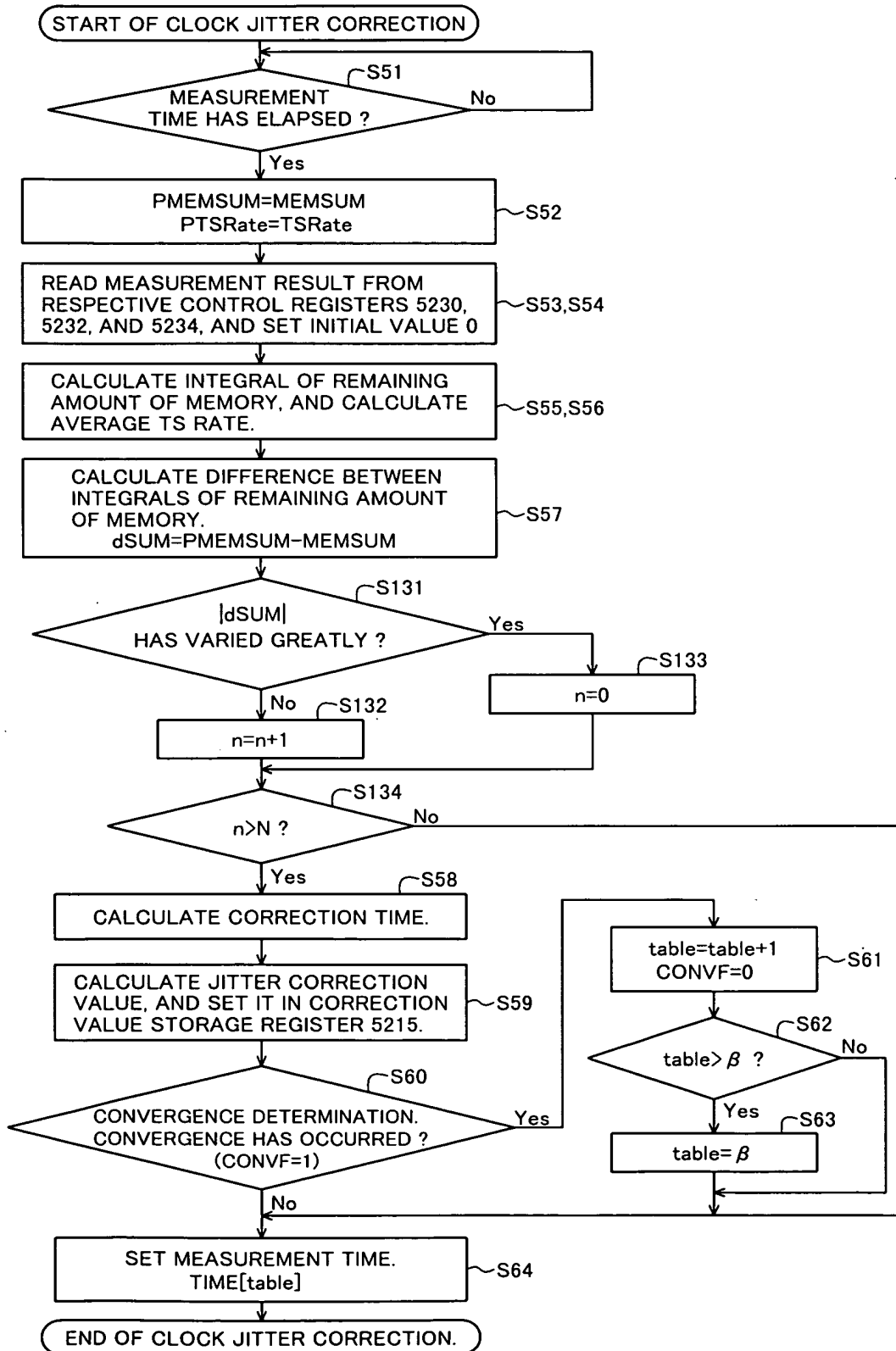


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FIG.30

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FIG.31



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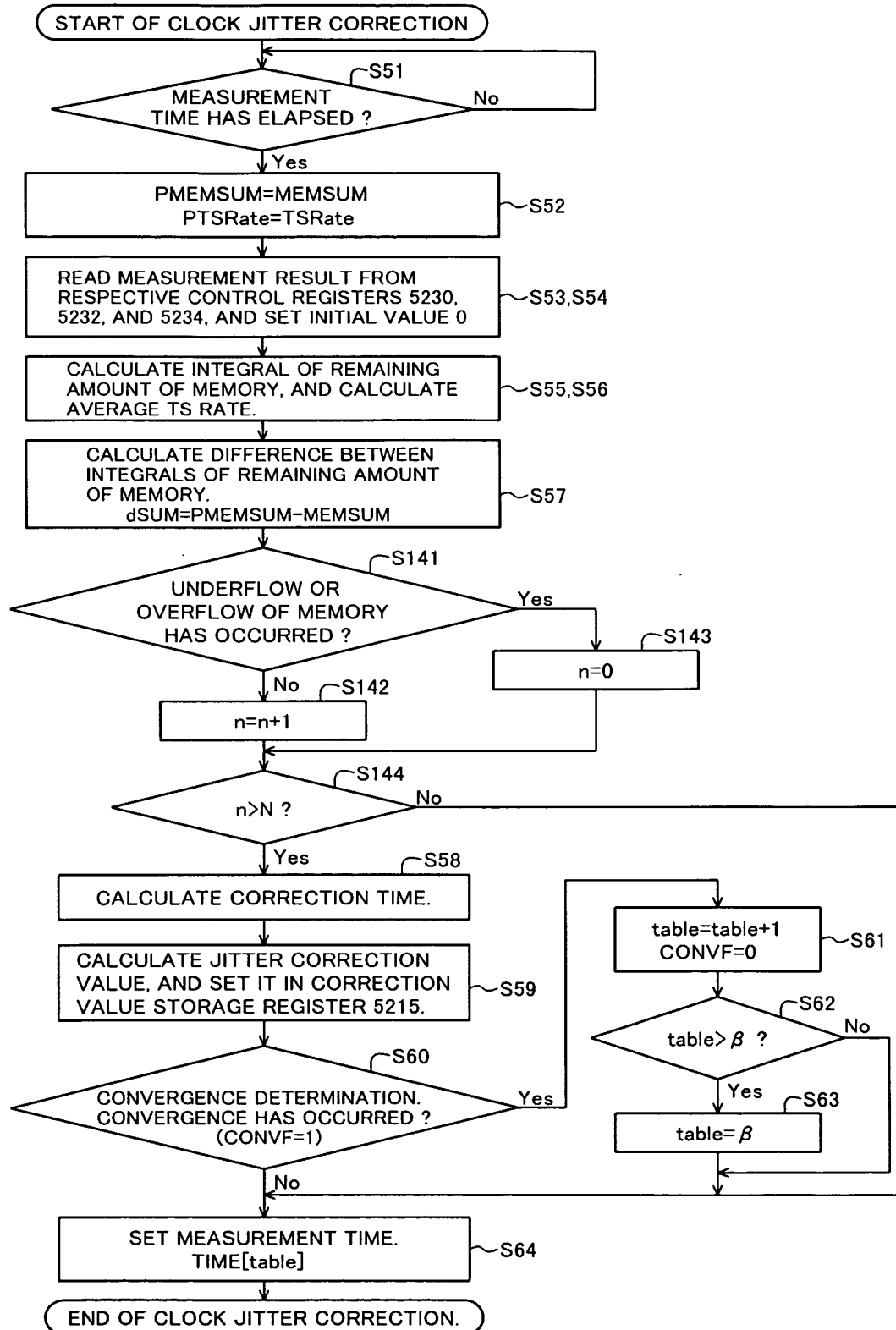
FIG.32

FIG.33A

TS
INPUT

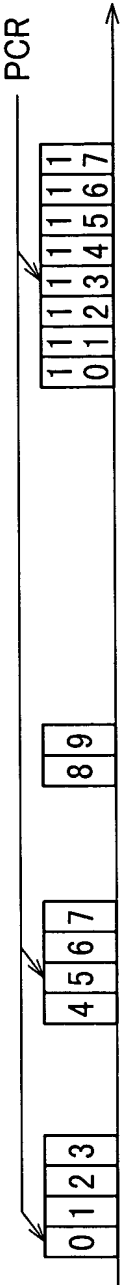


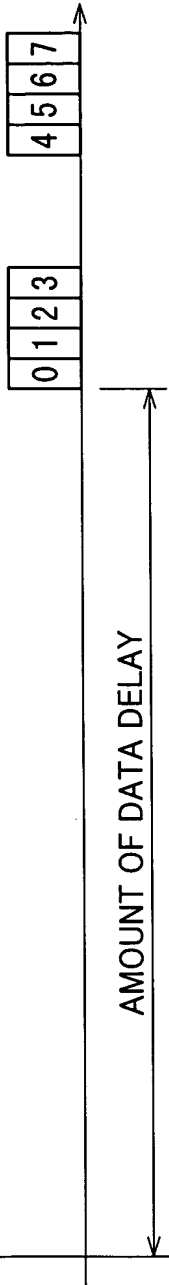
FIG.33B

WIRELESS
TRANS-
MISSION



FIG.33C

TS
OUTPUT



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FIG.34

